# **Benign Oscillation of Stochastic Gradient Descent with Large Learning Rate**











### **Motivation and Observations**

Large learning rate NN Training can result in better generalization. But why?

- Small LR training: curve is much smoother, converges more rapidly.
- Large LR training: an "oscillating" training curve, but better generalization!



### Strong feature v.s. Weak feature Model

- **Strong feature patch:** with probability  $1 \rho$ , this patch is strong feature  $y \cdot \mathbf{u}$ , otherwise this patch is a random noise
- **Weak feature patch:** always taken by the weak feature y
- **Random noise patch:** random Gaussian noise  $\boldsymbol{\xi}$  is randor sampled for the remaining patches

### Strong data:

- Has strong/weak feature
- Only appear with probability  $1 \rho$

### Weak data:

- Only has weak feature
- Every data has the weak feature

To generalize to **all** new data points, the NN must effectively learn the weak feature patch in face of the strong feature!

	a − 5° − − 1° − − 1° − 1° − 1° − 1° − 1°	Standarf ( an in Cine Connect Stand

Random noise

noise

Network on strong data with labe

$$f(\mathbf{w};\mathbf{x}) = \sum_{r=1}^{m} \sigma(\langle \mathbf{w}_r, \mathbf{u} \rangle) + \sigma(\langle \mathbf{w}_r, \mathbf{v} \rangle) +$$

Loss function:  $L(\mathbf{w}) = (f(\mathbf{w}; \mathbf{x}) - 1)^2$ 

## Miao Lu<sup>1</sup>, Beining Wu<sup>2</sup>, Xiaodong Yang<sup>3</sup>, and Difan Zou<sup>4</sup>

**Oscillation during training** can be closely tied to better generalization of SGD with Large LR!

What is the mechanism behind?

### Our Main Contributions:

- $\bullet$
- A new theoretical argument for feature learning driven by oscillation.
- Division for generalization by different learning rates.

### **Theoretical Demonstration and Finding**

### Why oscillation helps? A dynamic analysis

• Strong signal oscillation:  
• 
$$\sum_{s \in \delta^{-}} (1 - f(\mathbf{w}^{(s)}; \mathbf{x})) \cdot \langle \mathbf{w}_{r}^{(s)}, \mathbf{u} \rangle \approx \sum_{s \in \delta^{+}} (1 - f(\mathbf{w}^{(s)}; \mathbf{x})) \cdot \langle \mathbf{w}_{r}^{(s)}, \mathbf{u} \rangle$$
  
• **v**.  
• **Accumulation of negative updates**  
Since larger  $\langle \mathbf{w}^{(s)}, \mathbf{u} \rangle$  implies larger  $f(\mathbf{w}^{(s)}; \mathbf{x})$ , we have  
 $\sum_{s=t_{0}}^{t_{1}} (1 - f(\mathbf{w}^{(s)}); \mathbf{x}) = \Omega(\delta) \cdot (t_{1} - t_{0}))$  Oscillation  
accumulates  
• **Weak signal learning:**  
 $\sum_{s=t_{0}}^{t_{1}} (1 - f(\mathbf{w}^{(s)}; \mathbf{x})) \cdot \langle \mathbf{w}_{r}^{(s)}, \mathbf{v} \rangle \approx \sum_{s=t_{0}}^{t_{1}} (1 - f(\mathbf{w}^{(s)}; \mathbf{x})) \cdot \langle \mathbf{w}_{r}^{(t_{0})}, \mathbf{v} \rangle$   
e  $\xi$   
Longer oscillation implies larger  
weak signal learning:  
 $\sum_{s=t_{0}}^{t_{1}} (1 - f(\mathbf{w}^{(s)}; \mathbf{x})) \cdot \langle \mathbf{w}_{r}^{(s)}, \mathbf{v} \rangle \approx \sum_{s=t_{0}}^{t_{1}} (1 - f(\mathbf{w}^{(s)}; \mathbf{x})) \cdot \langle \mathbf{w}_{r}^{(t_{0})}, \mathbf{v} \rangle$   
E 1:  
• **Division of generalization properties**

- **SGD**, large LR: learns both strong/weak features.
- SGD, small LR: only learns the strong feature.

This explains why SGD with large LR can generalize better!

### **Our Key Message**

The oscillation prevents the over-greedy convergence and serves as the engine that drives the learning of less-prominent data pattern.

Allow for all useful data patterns to be discovered and learned :) These data patterns are beneficial for the NN to generalize to unseen data! We refer to such a phenomenon as "benign oscillation".

Dynamic analysis framework for SGD with large learning rates.

### Experimental verification

Illustrative setup: single data with two patches

### SGD with large learning rate:



Both strong and weak features are learned.

### SGD with small learning rate:



- Convergence is smooth.
- **Only** strong feature is learned.